

MARITIME ROBOTICS

lilafisch



- 32c3: Graphs, Drones and Phones
- 32c3: So you want to build a satellite
- 32c3: REXUS/BEXUS – Rocket and Balloon Experiments for University Students
- 31c3: Rocket science – how hard can it be?
- 31c3: Living Drones
- 31c3: Space Hacker
- 30c3: Drones
- 30c3: Die Drohnenkriege
- 30c3: Lasers in space
- ...

Robots are crawling the lands...
And flying through the air...
Some of them even made it to space...
So what about the sea?

Gated Communities of the Oceans



- Oil & Gas
- Military
- Other resource mining (fish, diamonds, minerals ...)

Image from http://www.macleans.ca/wp-content/uploads/2013/04/MAC16_OILRIGS01www.jpg

Hackers, I call thee to our oceans,
where (while?) there are still dragons to find!



The Squidworm - A New Species ✕

The squidworm (*Teuthidodrilus samae*), a swimming polychaete, was first discovered by Census of Marine Life researchers in the Celebes Sea at about 2800 meter depth in 2007.

Credit:

L. Madin, Woods Hole Oceanographic Inst. (WHOI)

(www.cmarz.org)

Image sources (in order of appearance):

- <http://ocean.si.edu/slideshow/census-marine-life-wild-and-wonderful-creatures>
- <http://www.montereybayaquarium.org/animals-and-experiences/exhibits/mission-to-the-deep>
- <https://twitter.com/expeditionlog/status/520233310753419265>

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Flapjack Octopus

Opisthoteuthis sp.

This cool-looking creature belongs to an unusual group of octopuses that have webbing between their arms. Often observed sitting on the seafloor, this octopus swims by flapping its fins to hover just above the bottom. It can pulse the web of arms and push water through its funnel for more rapid escapes. MBARI scientists think this is a new species of flapjack octopus. We've collected some specimens to study here at the Aquarium.

Depth range: 984 to 1,476 ft. (300 to 450 m)

Size: diameter to 7 in. (18 cm)


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- <http://www.montereybayaquarium.org/animals-and-experiences/exhibits/mission-to-the-deep>
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Can we update the "95% unexplored oceans" meme, I wonder?
theconversation.com/just-how-little ...

Moon  100% mapped
...at ~100 m resolution (NASA)
& at ~7 m resolution? (China)

Mars  100% mapped
...at ~100 m resolution &
~60% at ~20 m resolution

Earth's ocean  ~~5% mapped~~
100% mapped at max ~5 km resolution
~10-15% mapped at ~100 m resolution
<0.05% mapped at 1-2 m resolution

RETWEETS 103 LIKES 58



8:24 AM - 9 Oct 2014

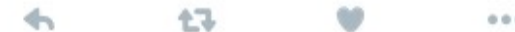


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And so much more to do!

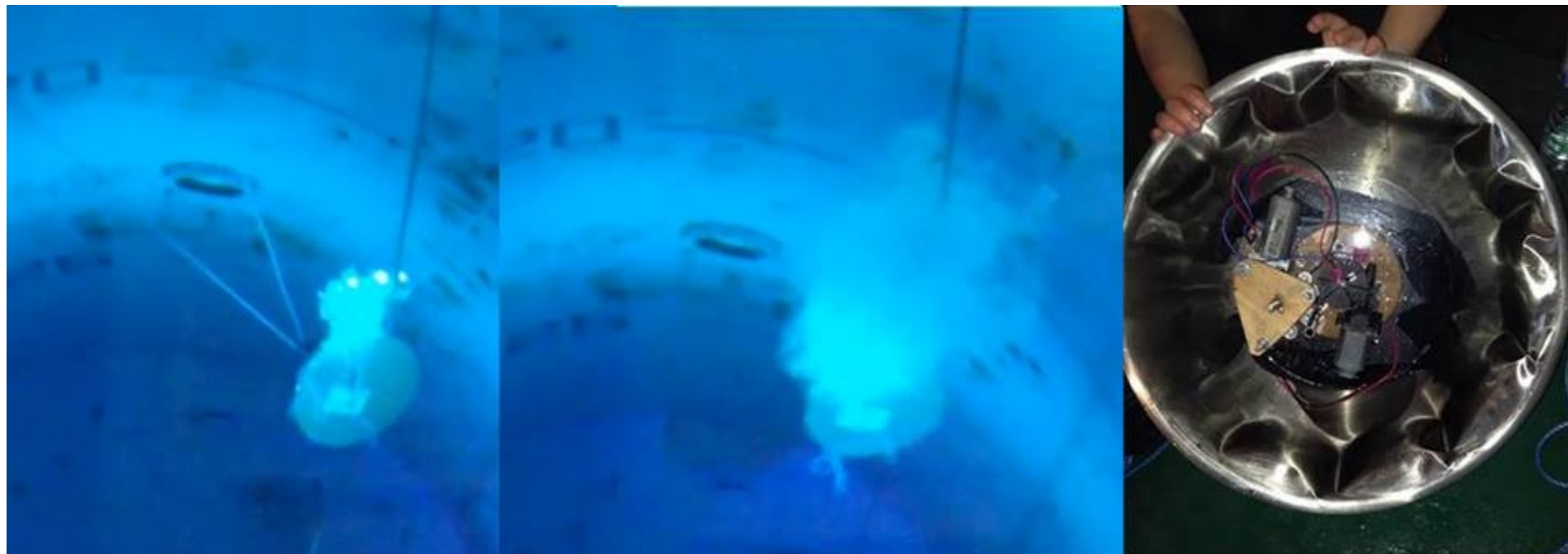
- Challenge – Because just building a robot isn't difficult enough!

TODO: FIND IMPRESSIVE PIC OF BROKEN MARITIME ROBOT!!!!!!

And so much more to do!

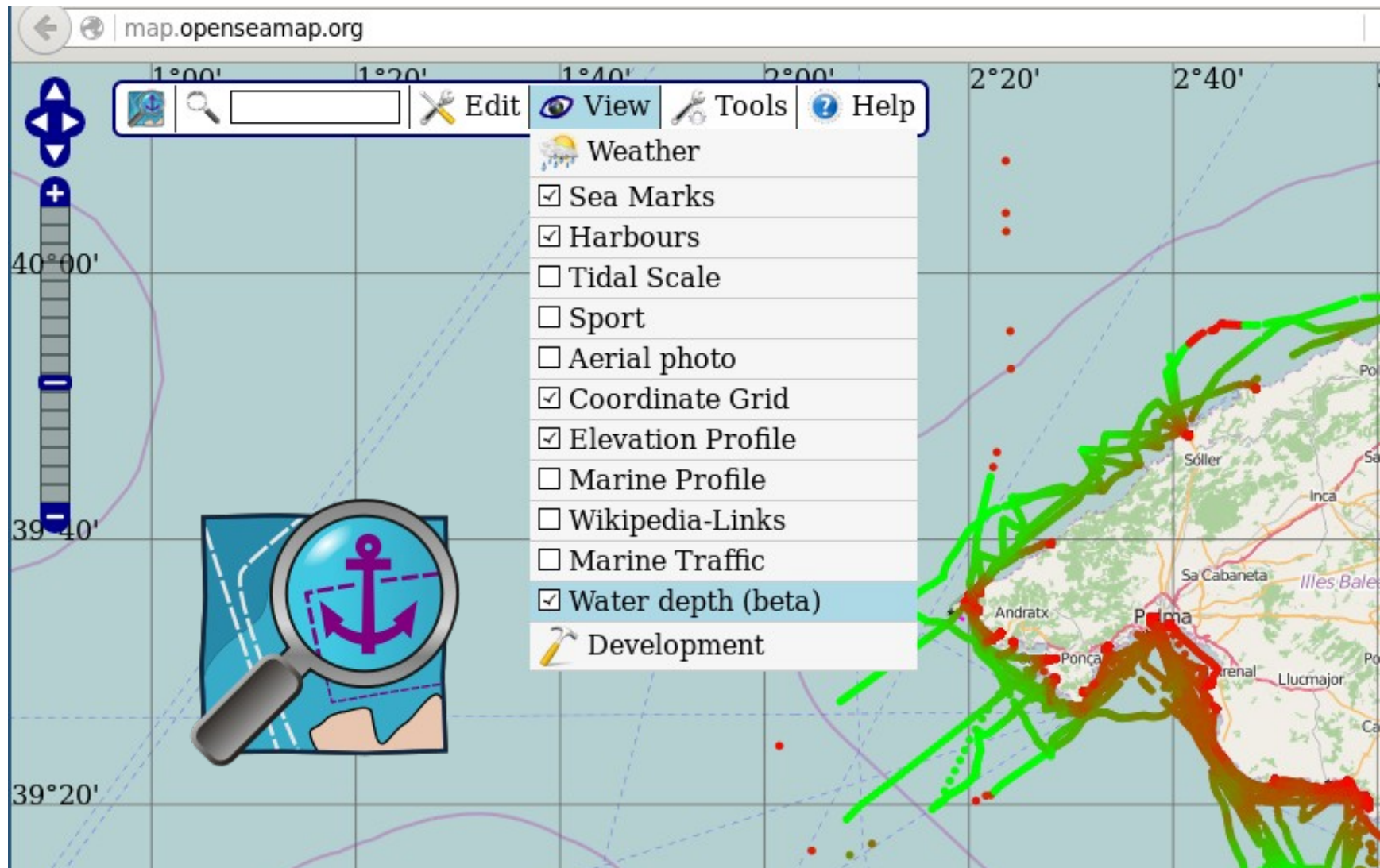
- Challenge – Because just building a robot isn't difficult enough!

TODO: FIND IMPRESSIVE PIC OF BROKEN MARITIME ROBOT!!!!!!



And so much more to do!

- Challenge
- Generate more data – And share it openly!



globalfishingwatch.org

AIS Automatic Identification System

The image shows a screenshot of the VesselFinder website. The ship information for the RANGER is displayed. The ship is a Container Ship. The tracking information shows the ship is sailing to Hamburg via NOK on Dec 29, 06:00. The current draught is 6.9 m. The ship's course is 356.9 degrees, speed is 8.8 kn, and gross tonnage is 7852 t. The ship was built in 2005 and has an IMO number of 9322542. The website URL is https://www.vesselfinder.com/.

Course	Speed	Current draught
356.9°	8.8 kn	6.9 m

Gross Tonnage	Built	IMO number
7852 t	2005	9322542

And so much more to do!

- Challenge
- Generate more data
- Archeology – Check out the hidden treasures in your nearest puddle/lake/ocean!



(Monkey Island 2 gameplay screenshot)

And so much more to do!

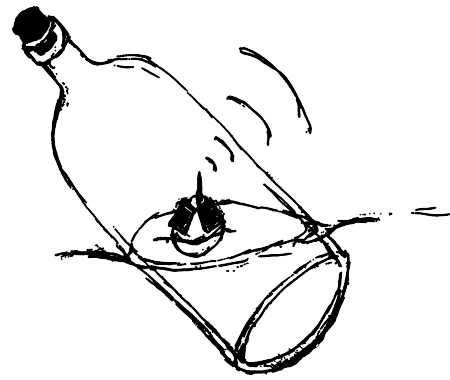
- Challenge
- Generate more data
- Archeology
- Environmental monitoring
 - Why does the water coming out of this pipe next door glow in the dark?



(Day of The Tentacle gameplay screenshot)

Maritime Robots Family Tree

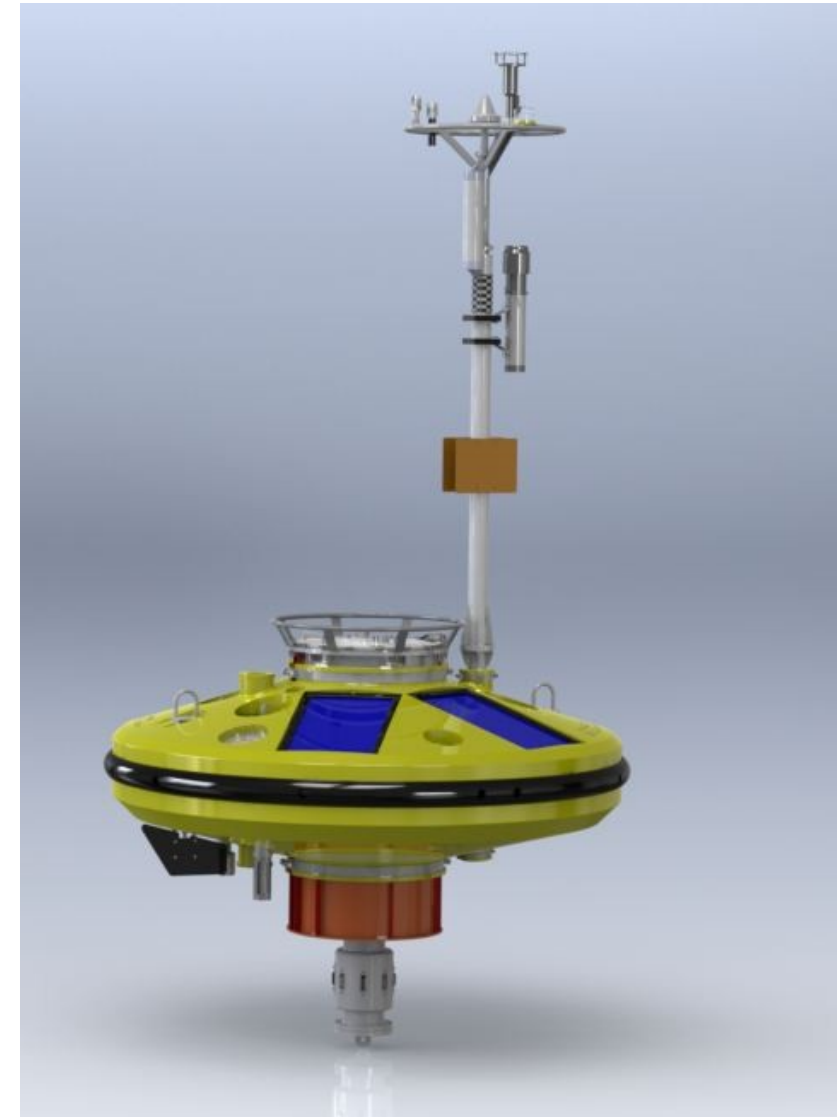
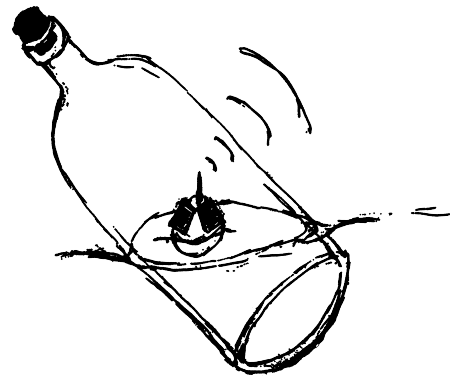
– The Sensor Buoy



<http://www.bornhoeft.de/en/newsneu.html>

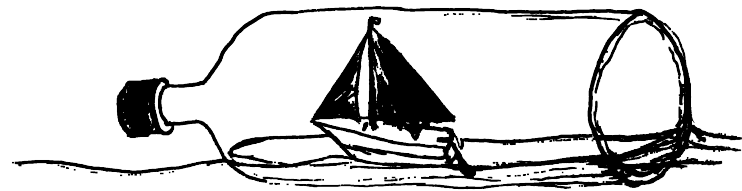
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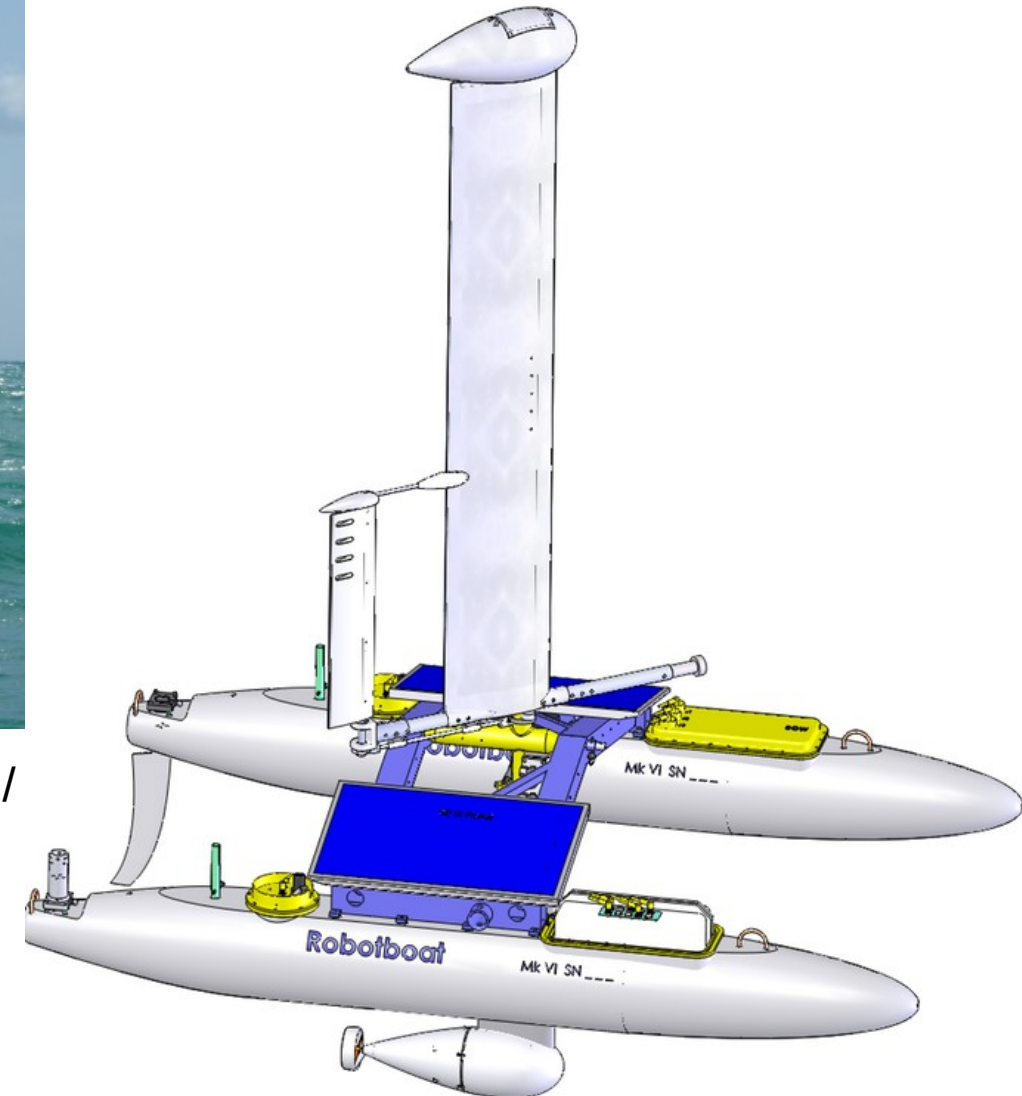


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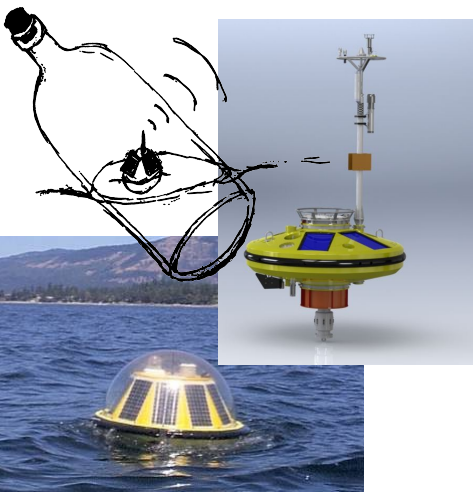
- The Sensor Buoy
- The Traveler



<http://www.automarinesys.com/recent-testing/>

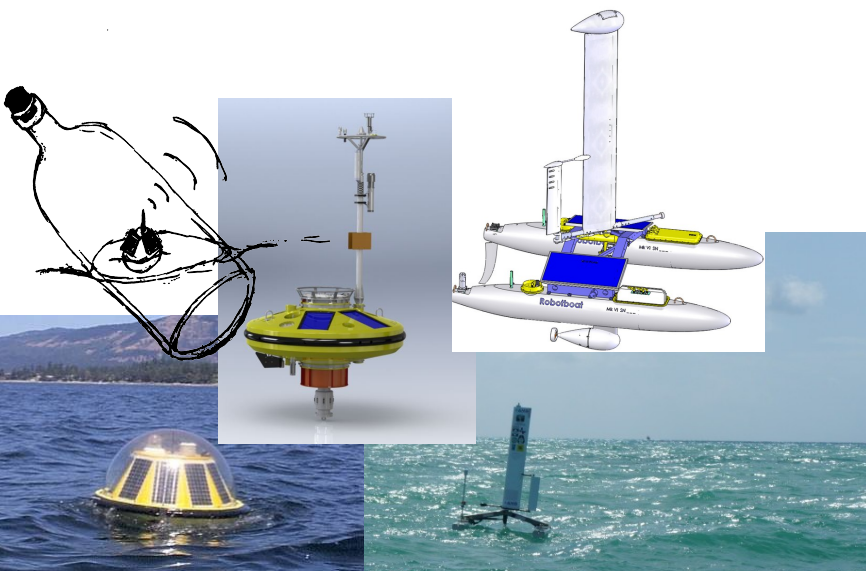
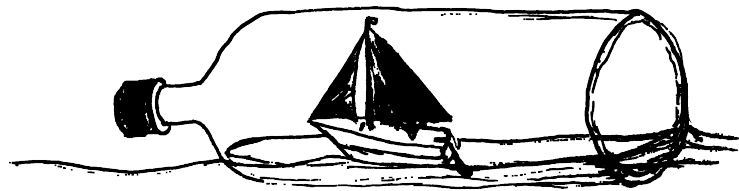


<https://www.kickstarter.com/projects/robotboat/robotboat-mark-vi/description>



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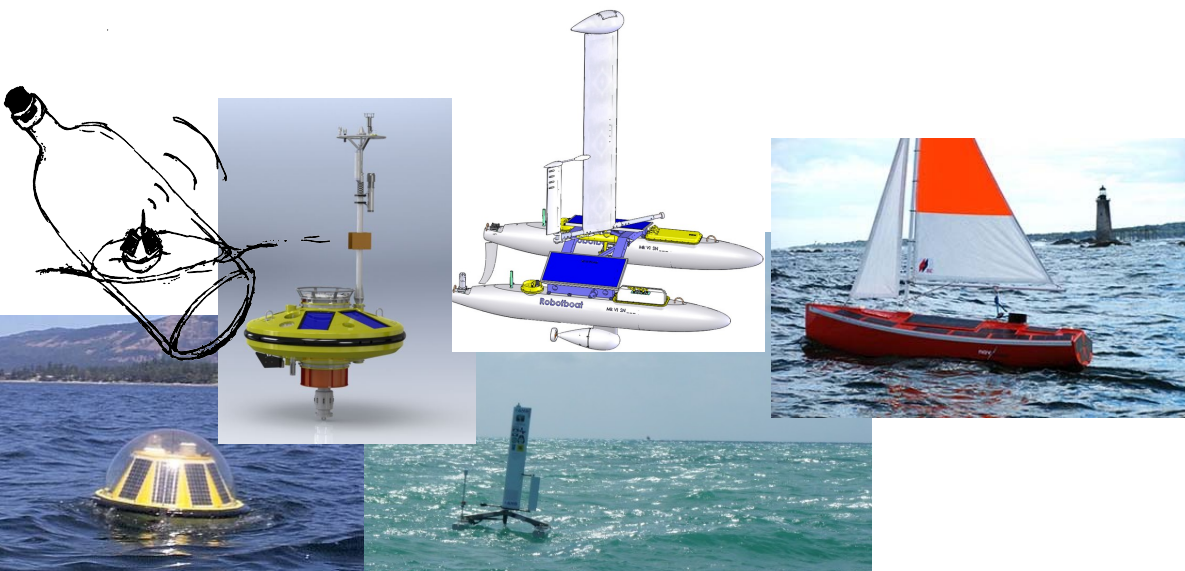
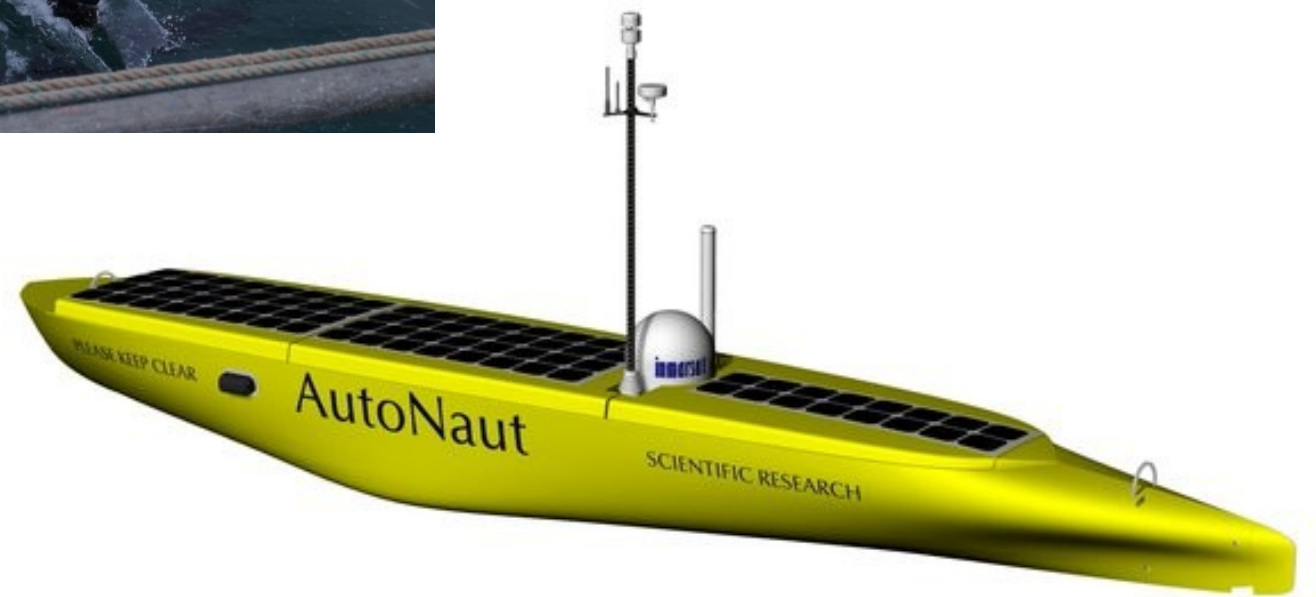
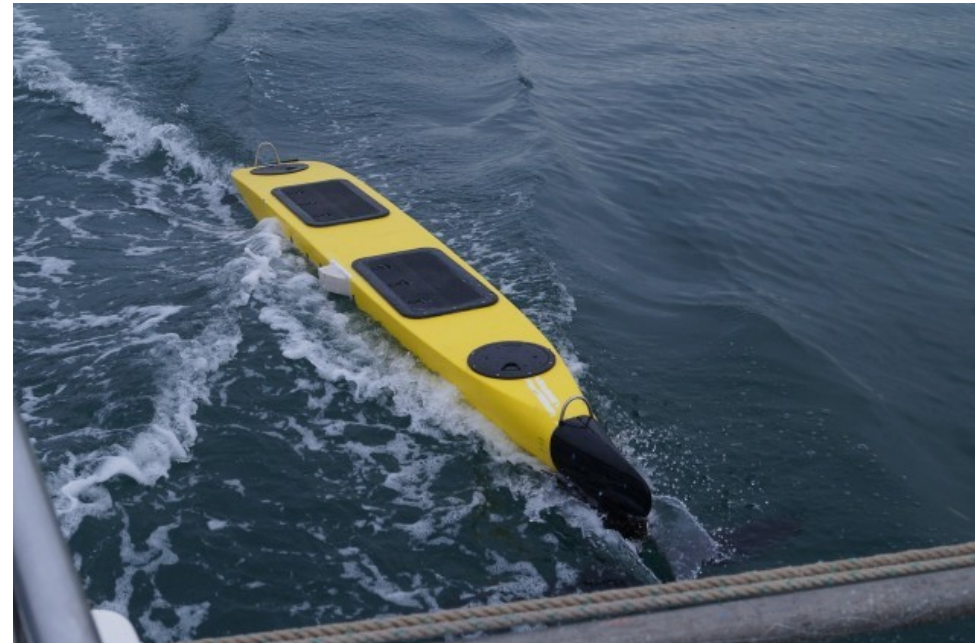
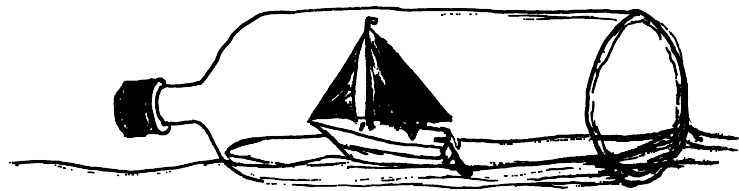
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<http://navocean.com/tag/waveglider/>

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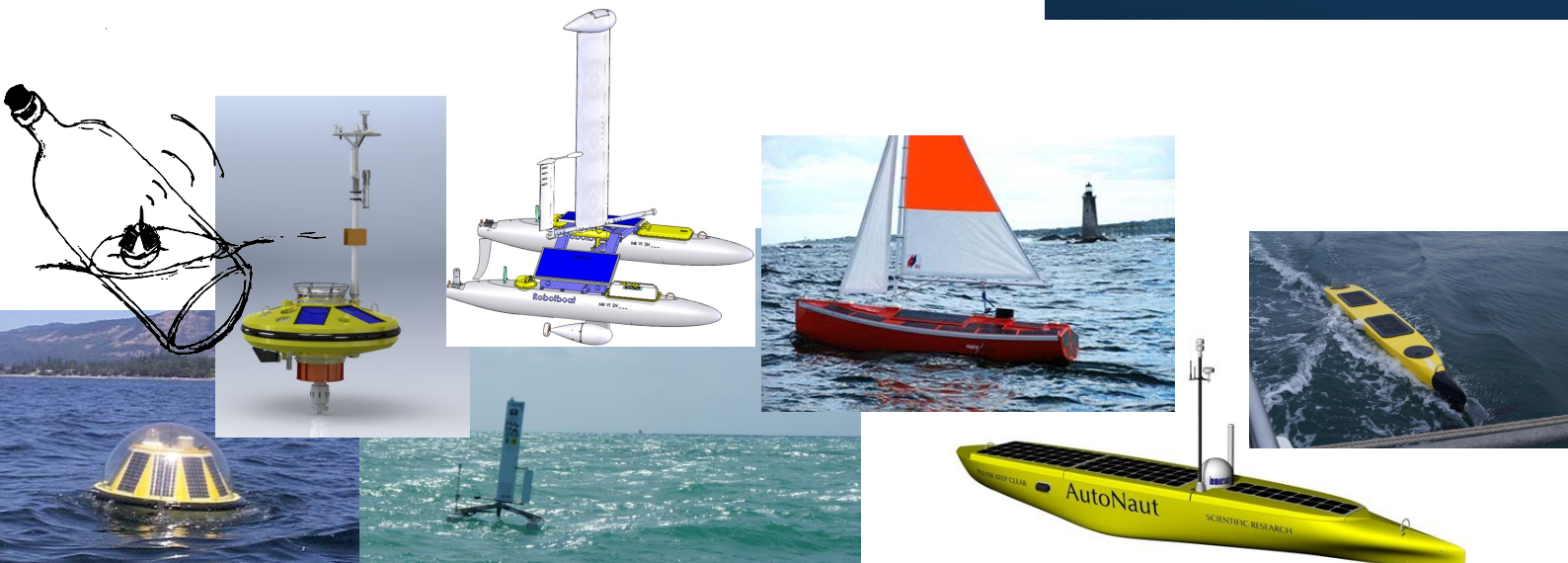
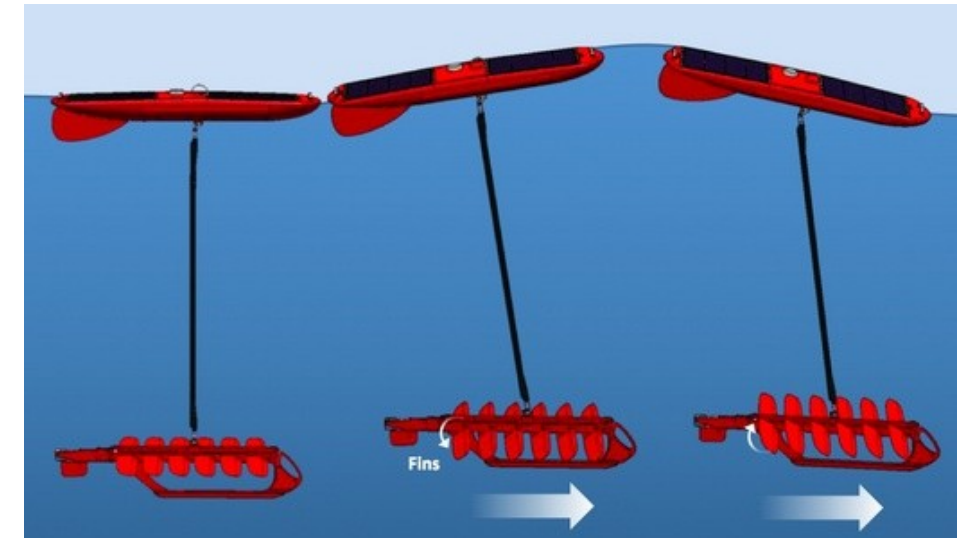
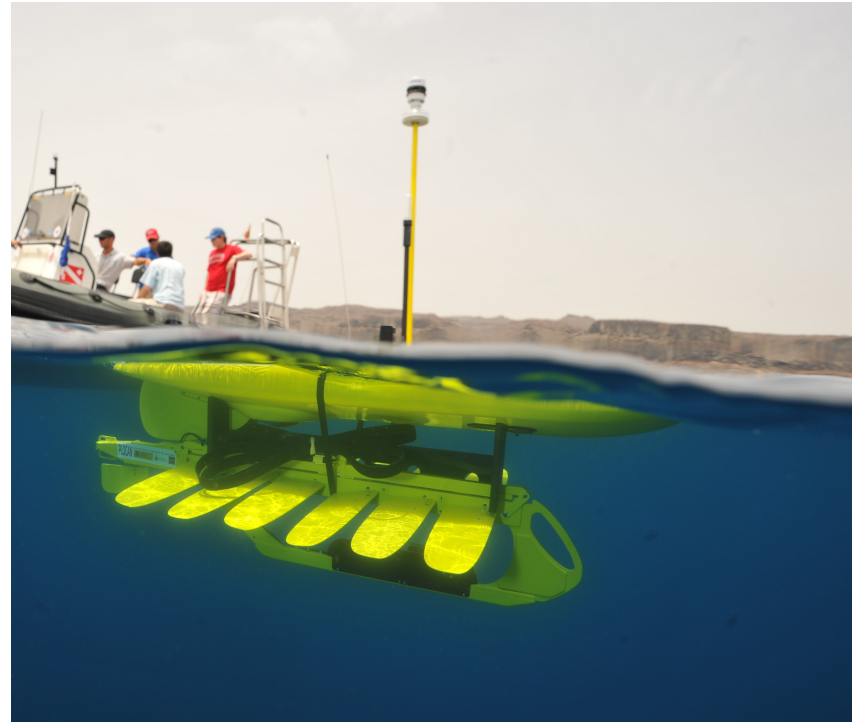
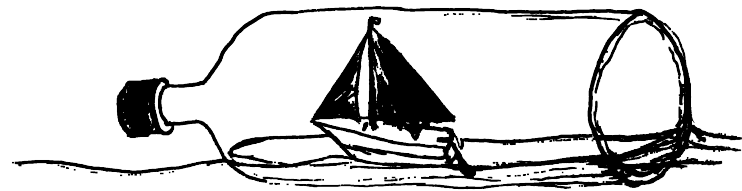
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- The Traveler



<http://www.autonautusv.com/wp-content/uploads/2013/11/DSC04717-800x530.jpg>
<https://twitter.com/AutoNautUSV/status/585437452254478336>

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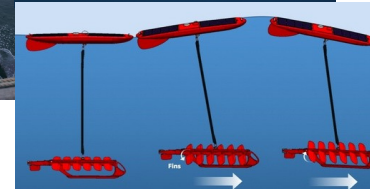
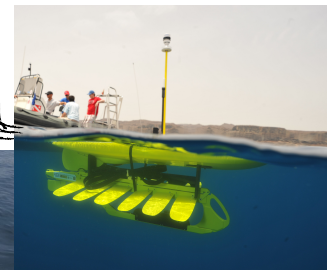
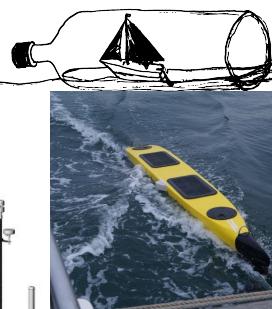
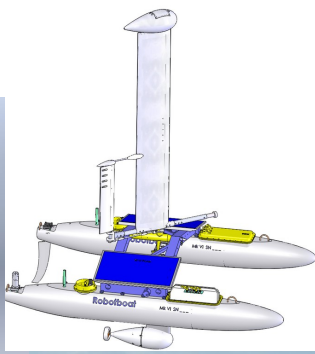
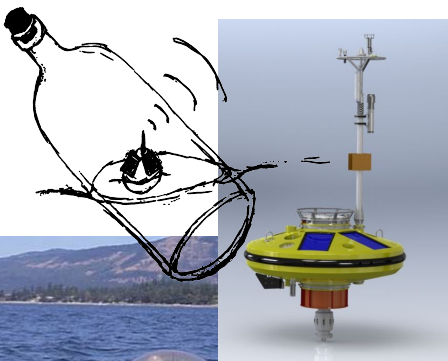
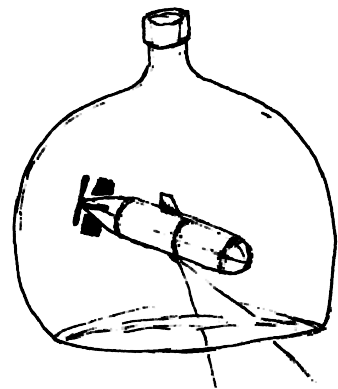
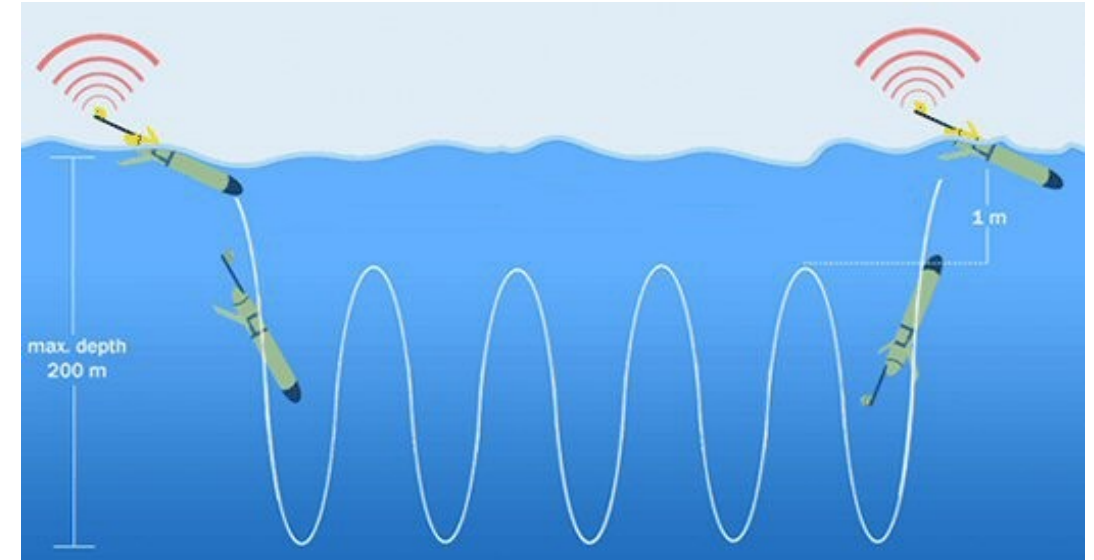


<https://cdn3.dogonews.com/pictures/9197/content/gliderWaveGliderMotion.jpg?1321224868>

<http://www.liquidr.com/images/galleryfull/lri-img-MidLaunchWaveGlider.jpg>

Maritime Robots Family Tree

- The Sensor Buoy
- The Traveler
- The Underwater Airplane

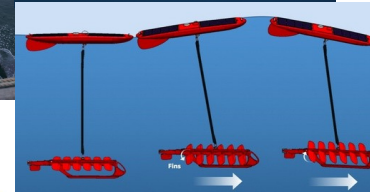
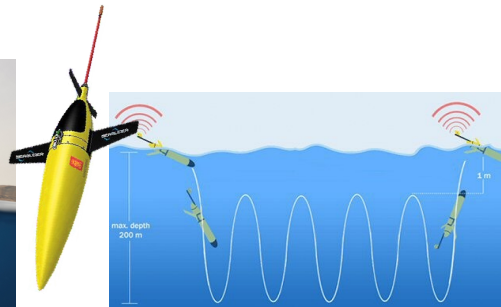
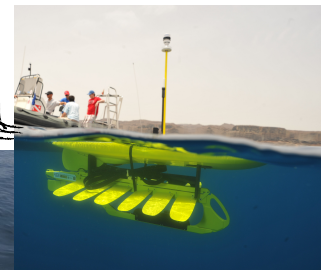
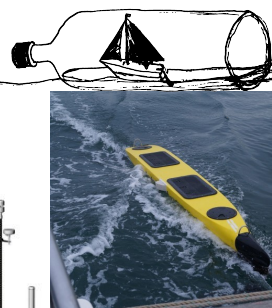
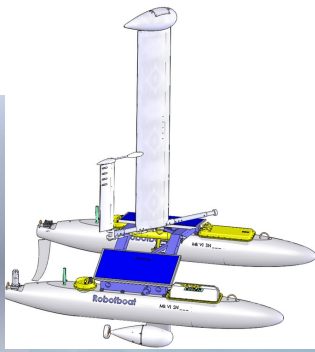
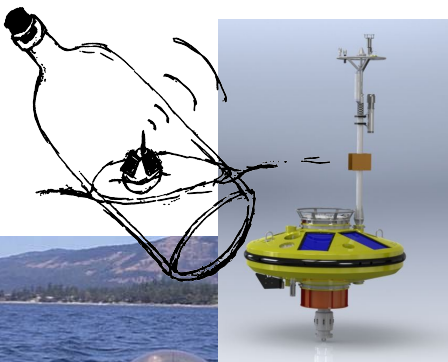
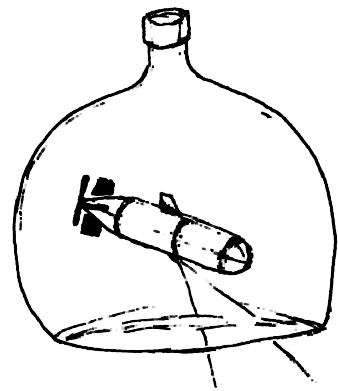


<http://auvac.org/platforms/view/160>

<http://cobs.noc.ac.uk/cobs/gliders/whatisaglider.php>

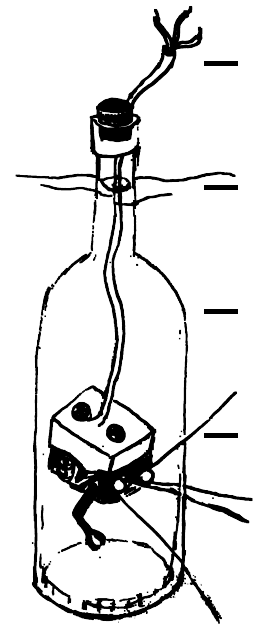
Maritime Robots Family Tree

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<http://noc.ac.uk/news/autosub-long-range-auv-completes-its-first-sea-trials>
<https://www.srcf.ucam.org/polarauvguide/aavs/caseStudies/usips.php>

Maritime Robots Family Tree



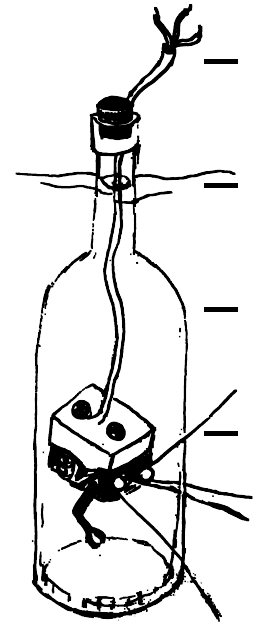
- The Sensor Buoy
- The Traveler
- The Underwater Airplane
- The Diving Box



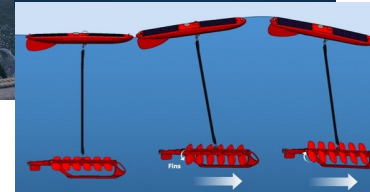
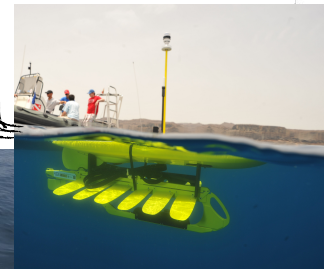
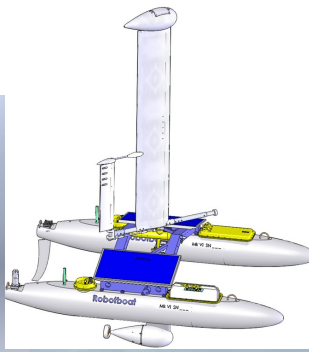
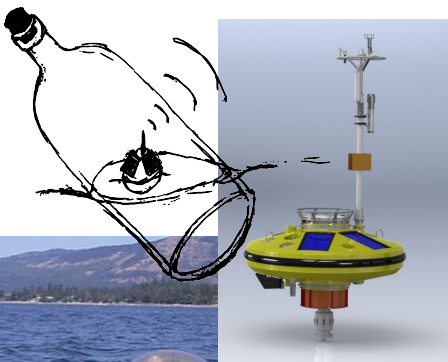
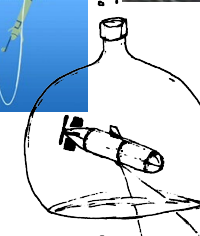
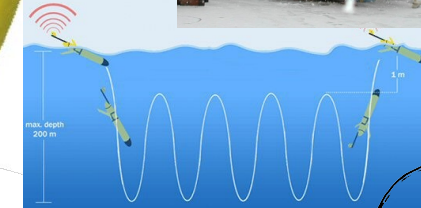
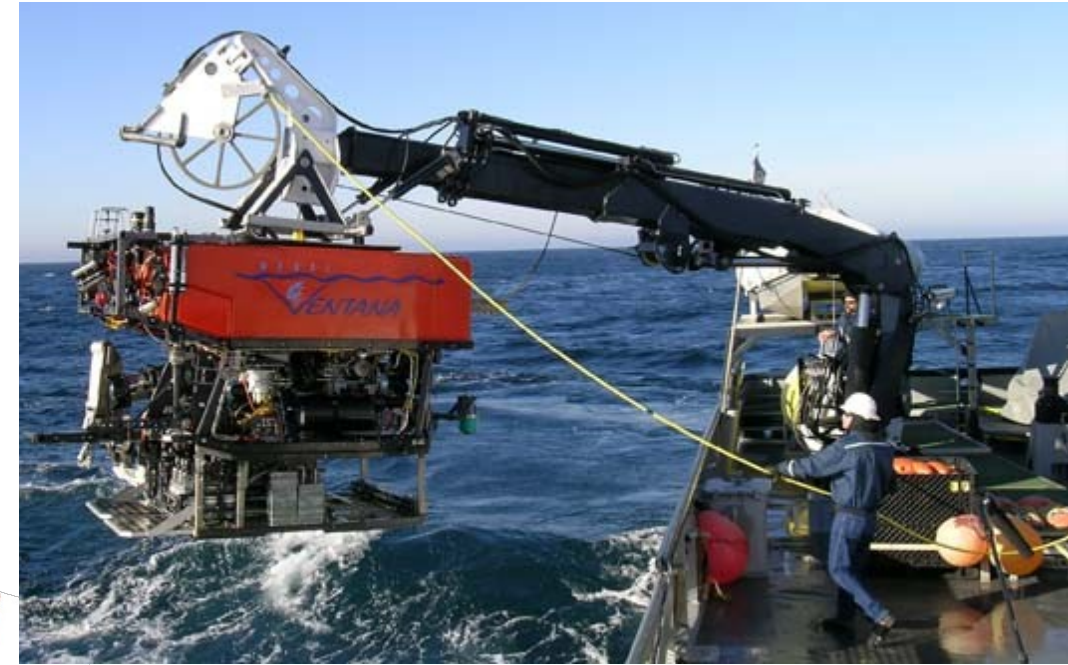
<http://www.auv2016.org/>



Maritime Robots Family Tree

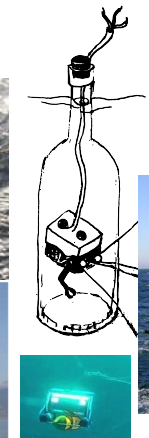
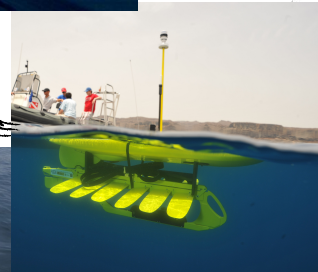
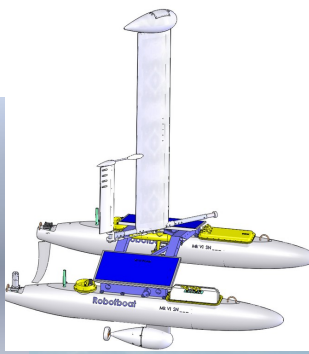
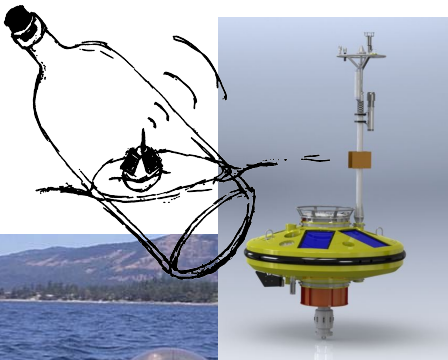
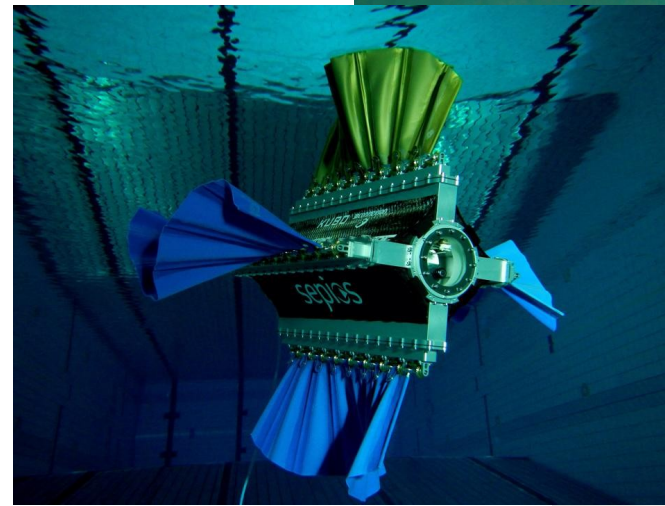
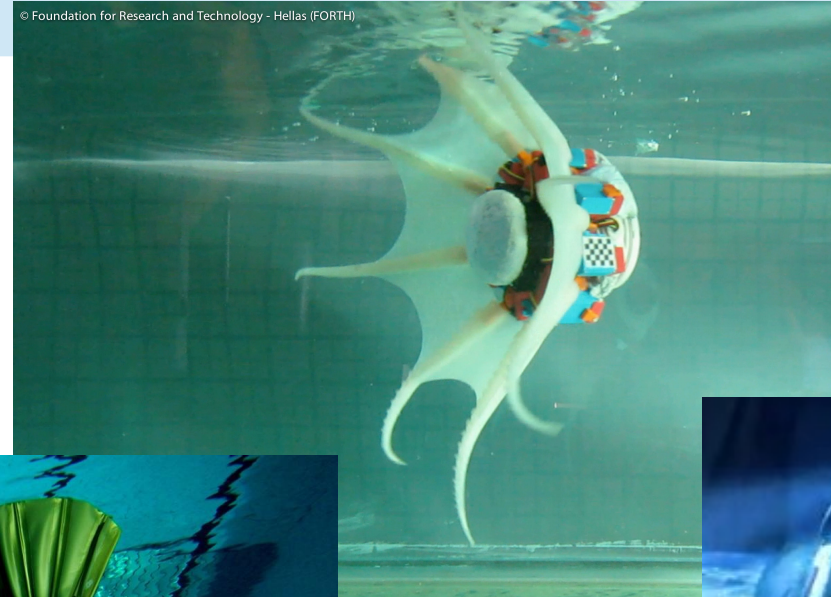


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- The Traveler
- The Underwater Airplane
- The Diving Box



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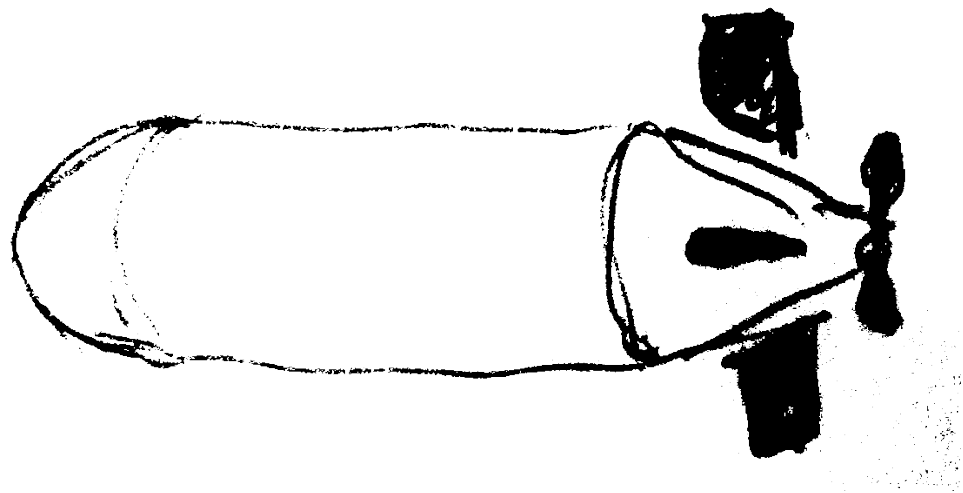
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- The Traveler
- The Underwater Airplane
- The Diving Box
- The Wild Cards



<http://sepios.org/>
<http://www.ics.forth.gr/cvri/octopus/gallery.html>
<http://scoutbots.com/blogs/news/15204209-test-of-protei-011-1-at-sea>
<http://mechatronic.me/robotics/74-underwater-walking-robot-crabster-cr200>

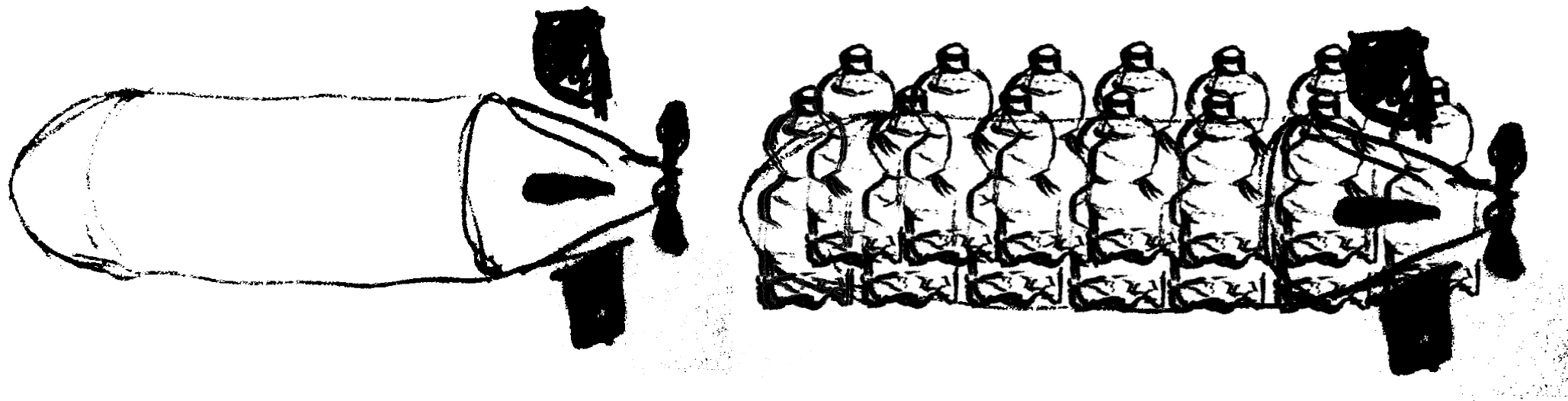
Buoyancy

- + You can be positive about your robot coming back.
- 0 Gravity free floating :D
- No need to feel negative, as long as you can drop some weight



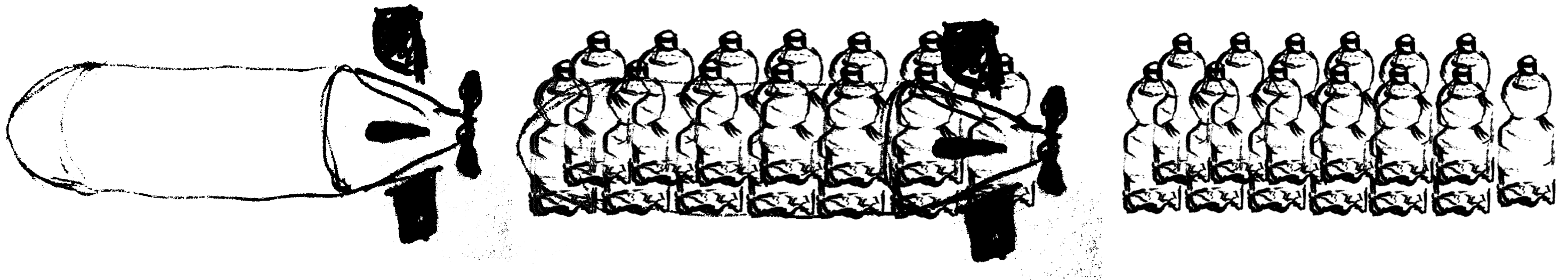
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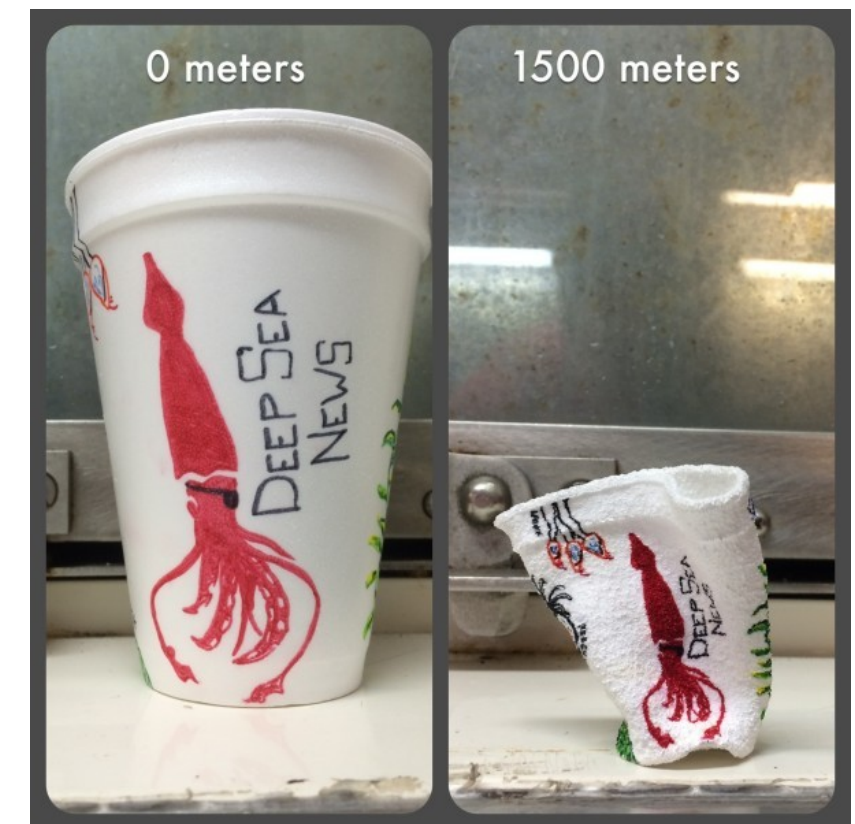
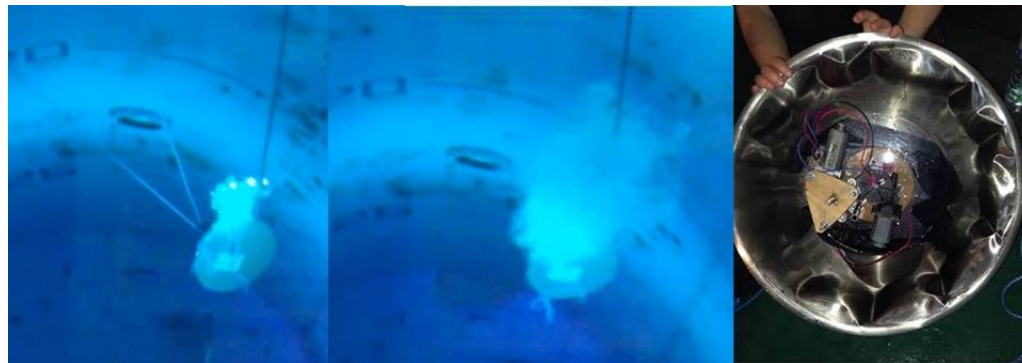
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Pressure

- Rule of thumb: Earth atmosphere $\hat{=}$ 10 metres water depth $\hat{=}$ 1 bar
- Buckling Pressure for Sphere $\sim \left(\frac{\text{Thickness}}{\text{Radius}} \right)^2$
- Ping pong balls: \sim 25 m depth
- Average Ocean Depth: 4 km
- Maximum Ocean Depth: 11 km

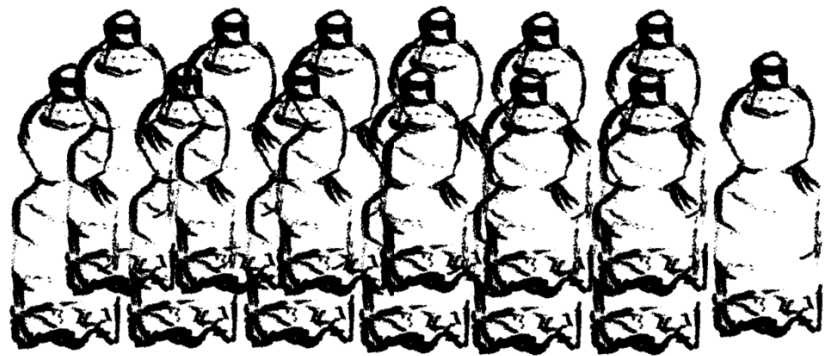


http://kwc.org/mythbusters/2004/11/mythbusters_ping_pong_balls_an.html

<http://www.deepseanews.com/2014/05/how-to-shrink-a-styrofoam-cup-and-other-side-effects-of-deep-ocean-pressure/>

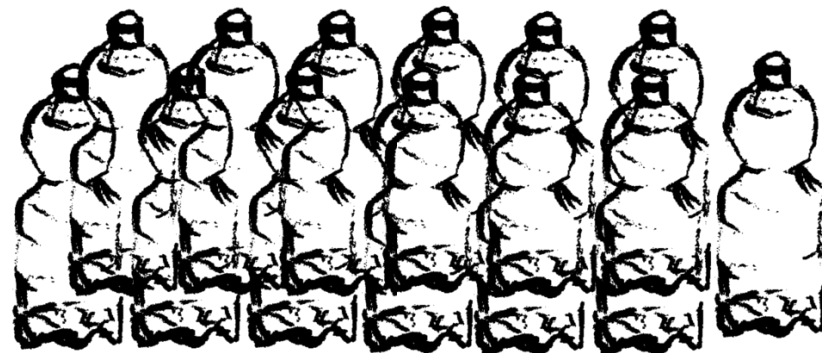
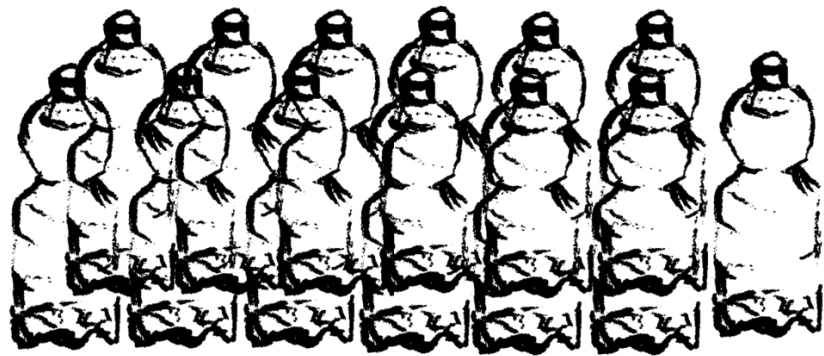
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Robotic Deep-sea Vehicle Lost on Dive to 6-Mile Depth

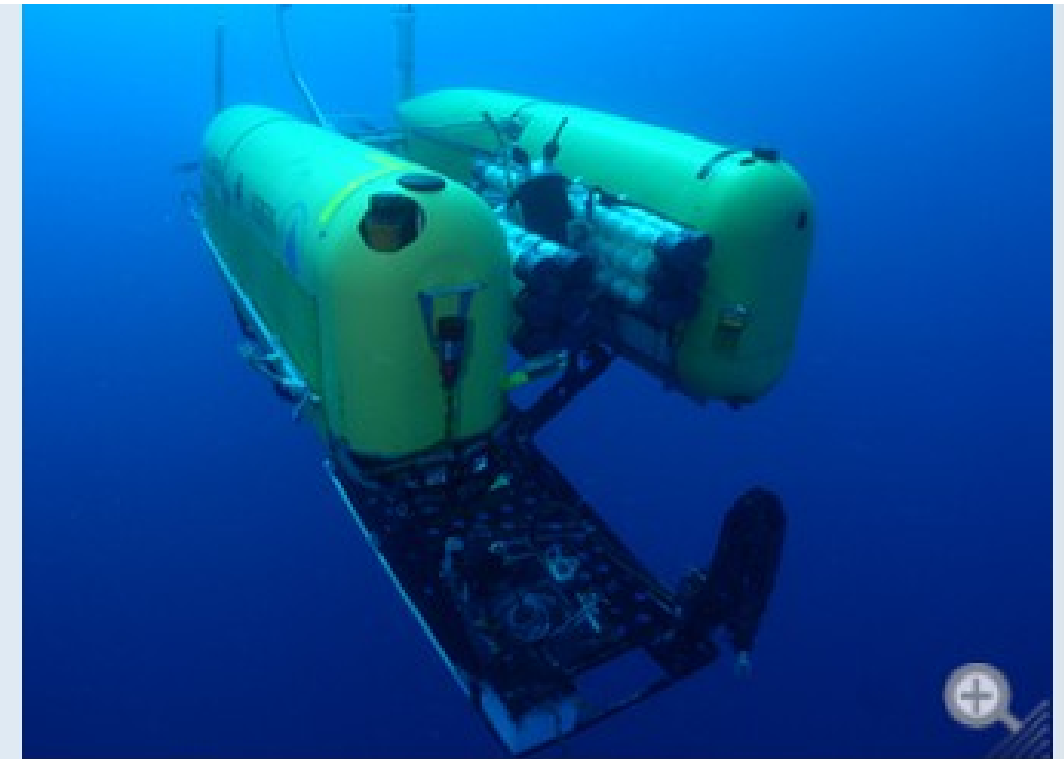
Scientists think *Nereus* imploded exploring the Kermadec Trench

FOR IMMEDIATE RELEASE

May 10, 2014
(508) 289-3340

Media Relations Office
media@whoi.edu

On Saturday, May 10, 2014, at 2 p.m. local time (10 p.m. Friday EDT), the hybrid remotely operated vehicle *Nereus* was confirmed lost at 9,990 meters (6.2 miles) depth in the Kermadec Trench northeast of New



Nereus's mission was to undertake high-risk, high-reward

<http://www.whoi.edu/news-release/Nereus-Lost>

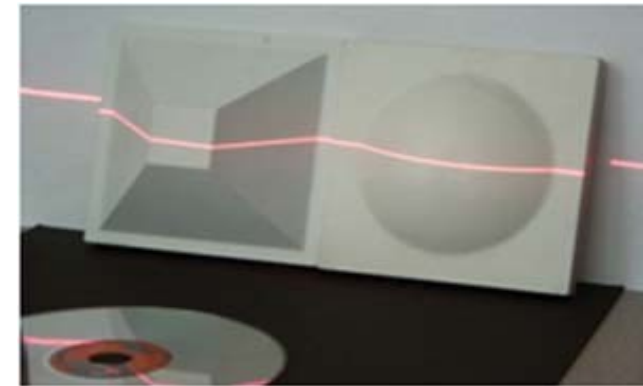
Communication & Orientation

Sensor Buoy & Traveler:

- GPS & Wireless communication (→ iridium SBD)

Underwater Airplane & Diving Box: Goodbye radio waves...

UV/blue best candidate in EM spectrum



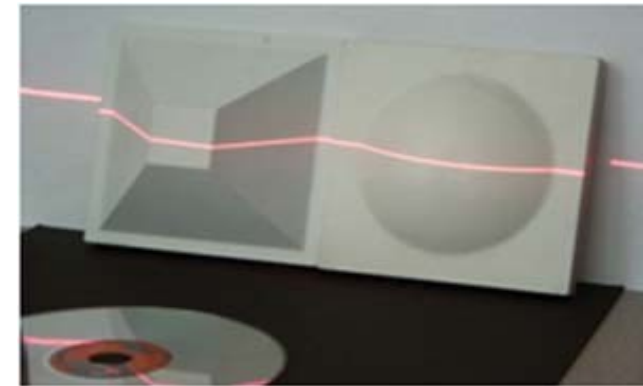
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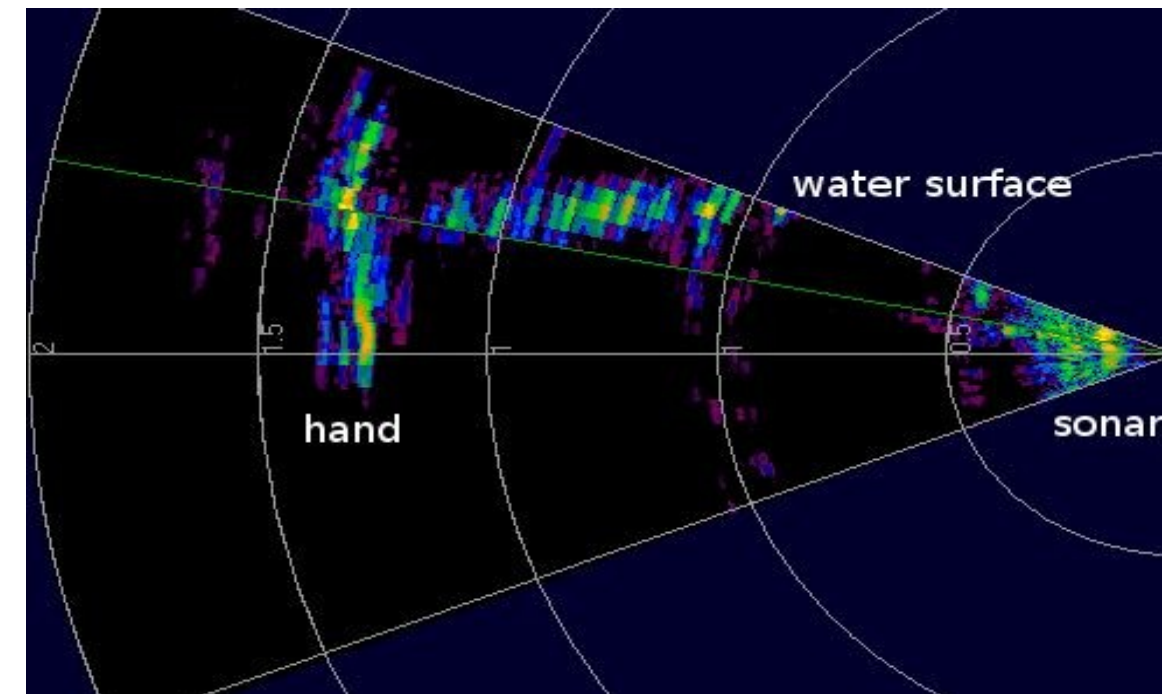
- GPS & Wireless communication (→ iridium SBD)

Underwater Airplane & Diving Box:

Goodbye radio waves...

UV/blue best candidate in EM spectrum

... hello acoustic waves

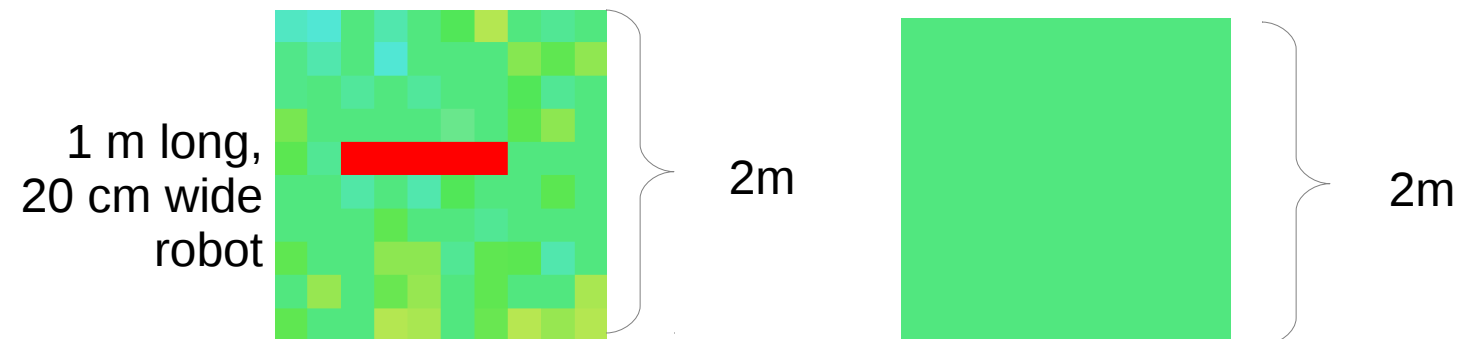


Sonar

Speed of sound in water: ~ 1500 m/s (light speed: $3 \cdot 10^8$ m/s)

Beam opening angle: 1 degree \rightarrow Pixel width: $\sin(1^\circ) * \Delta x$

- 10 m: ~ 20 cm
- 100 m: ~ 2 m

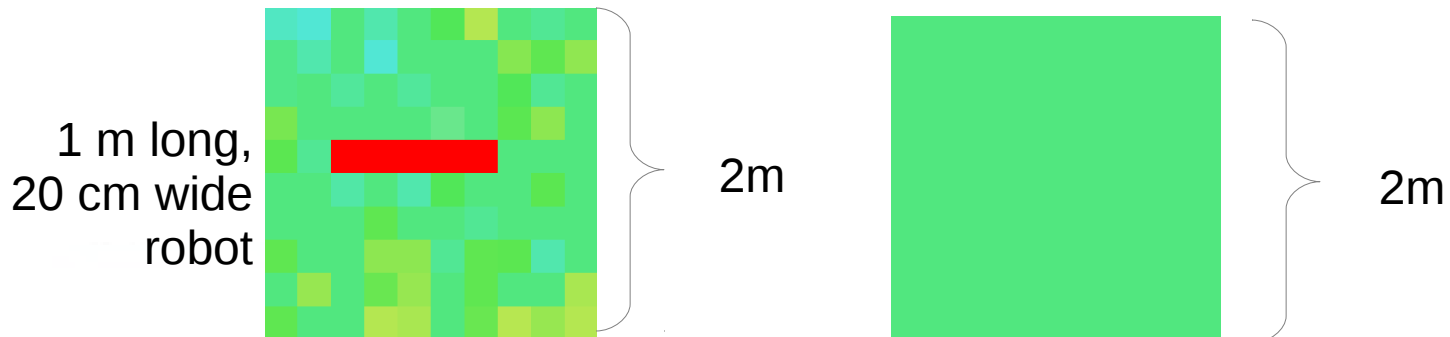


Sonar

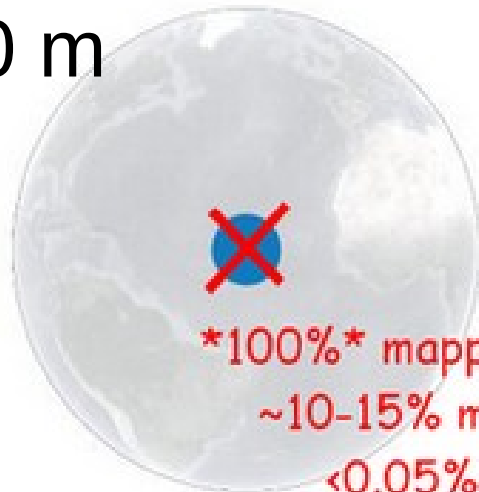
Speed of sound in water: ~ 1500 m/s (light speed: 3×10^8 m/s)

Beam opening angle: 1 degree \rightarrow Pixel width: $\sin(1^\circ) * \Delta x$

- 10 m: ~ 20 cm
- 100 m: ~ 2 m
- 10 km: ~ 200 m



Earth's ocean



~~5% mapped~~

**100%* mapped at max ~ 5 km resolution
 $\sim 10-15\%$ mapped at ~ 100 m resolution
 $< 0.05\%$ mapped at 1-2 m resolution*

Listen!

- Communication of robots, animals
- Changes in sound propagation (~ salinity, temperature, 'stuff')
- The lower the frequency, the further it travels
- Noise:
 - Wind, Waves, Earthquakes
 - Propeller, Engine, other human noise
 - Dragons

- **Whale song listening!**

<http://www.oceannetworks.ca/sights-sounds/live-audio/> : “Hydrophone recordings are not continually available because they may sometimes contain sensitive data with national security implications. ... Recordings that are deemed low risk are then returned to our archives at a later time.”

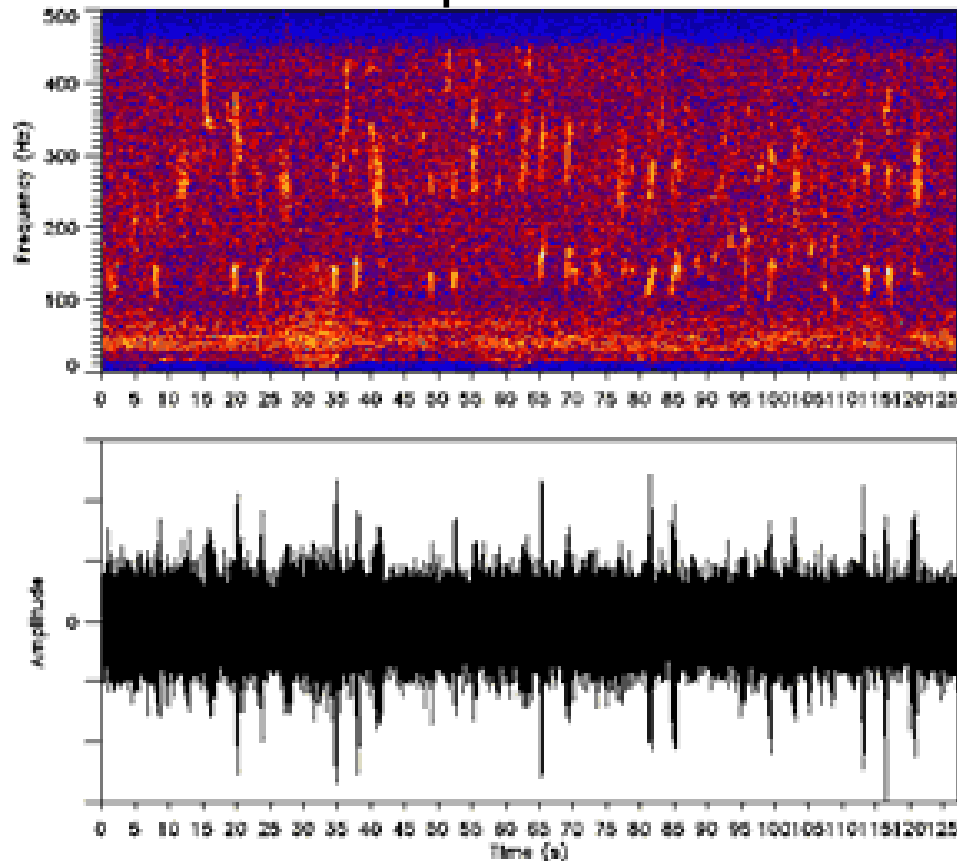
Listen to Mediterranean Sea
check species detected



<http://listentothedeep.com>

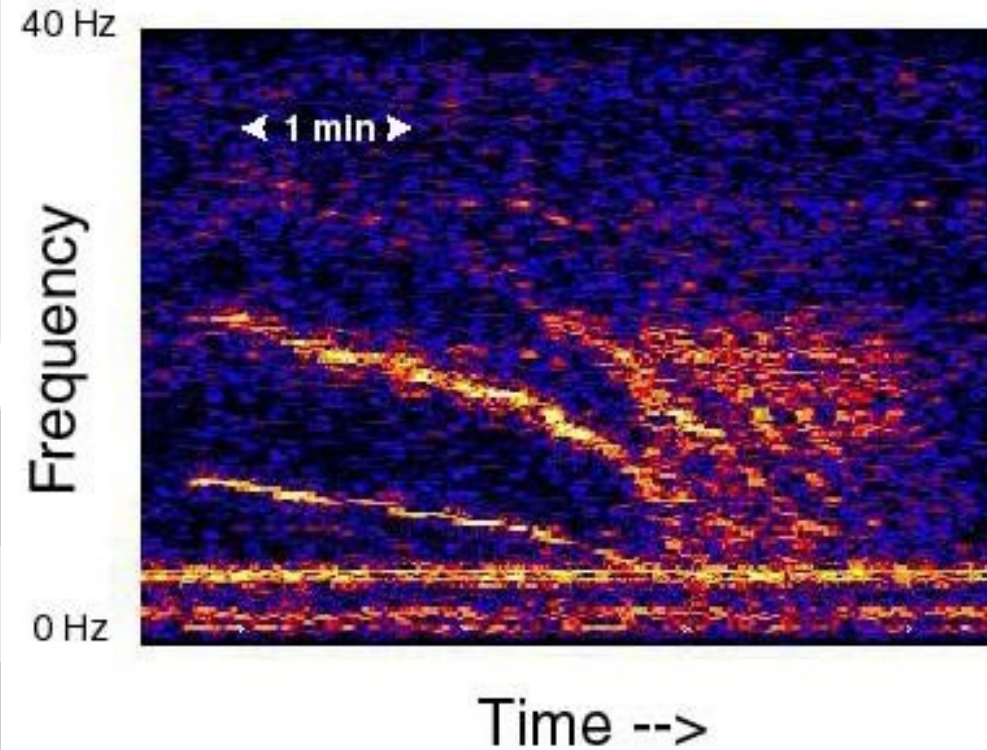
Listen!

Alaska humpback whale call



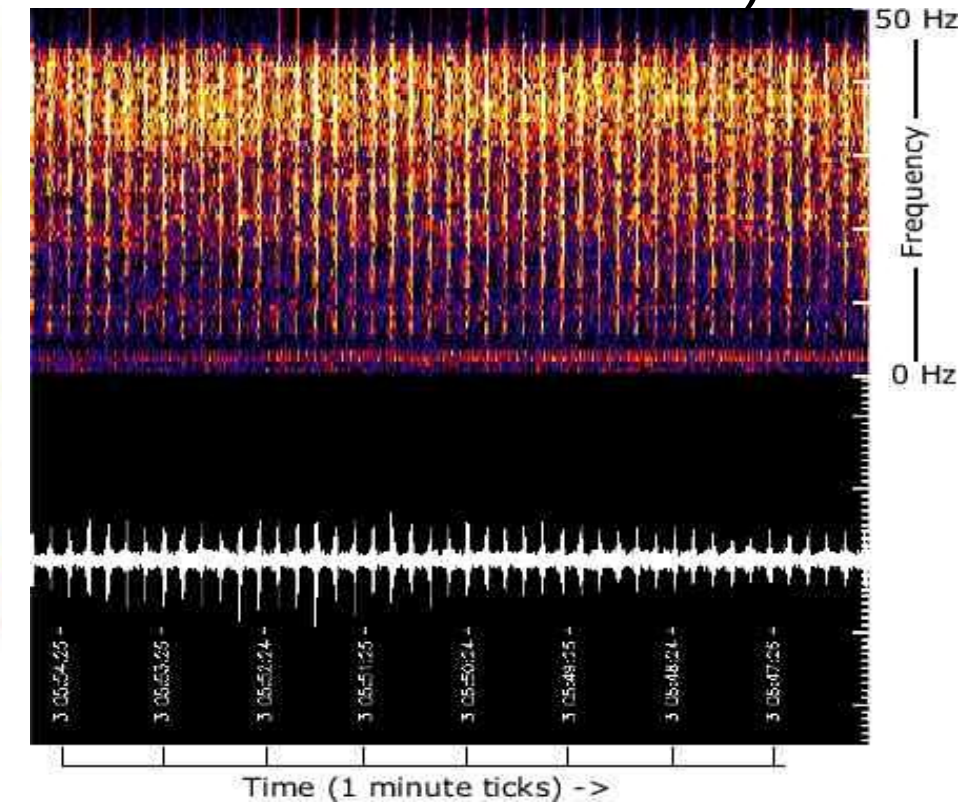
Sped up 10 times

Iceberg grounding on seafloor



Sped up 16 times

Airguns (explore geologic structure below seafloor)



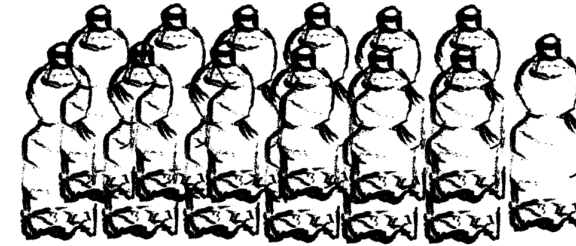
Sped up 10 times

Sounds and spectrograms from:

<http://oceanexplorer.noaa.gov/explorations/sound01/background/seasounds/seasounds.html>

Not all that difficult and expensive???

$$\text{Buckling Pressure} \sim \left(\frac{\text{Thickness}}{\text{Radius}} \right)^2$$

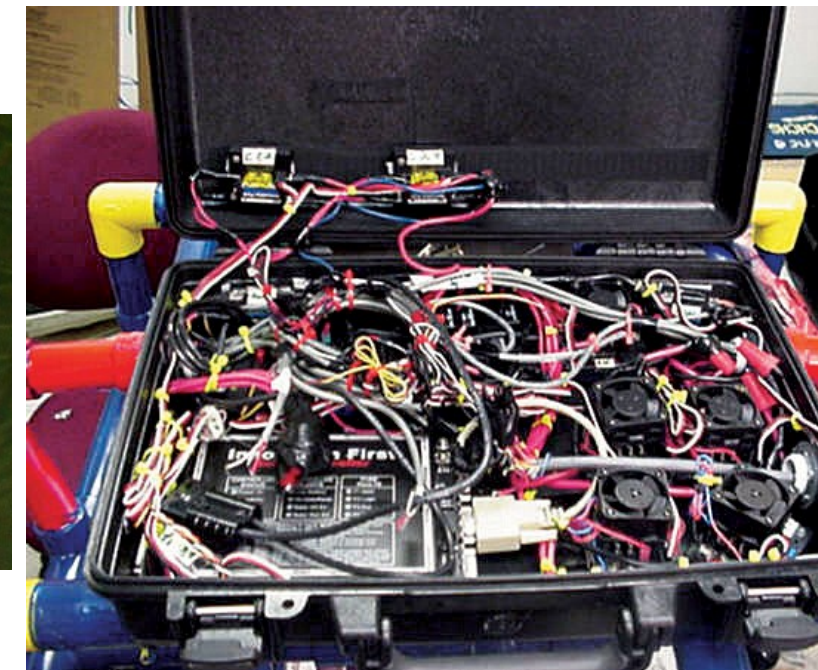


Size is (almost) all that matters!

- Small scale, low power consumption Linux computers
- High energy density batteries

→ Smaller, lighter vehicles can be tested in/on smaller puddles

- Model Boats
- Tupperware & Pelicase
- Pipes & Bottles
- Surringes
- Tampons
- Fishfinders
- Aquarian Audio



<http://www.seaglide.net/>

<http://www.wired.com/2014/12/4-mexican-immigrant-kids-cheap-robot-beat-mit>

Communities?

- Forums
 - <http://www.homebuiltrovs.com/rovforum/>
 - <https://forum.openrov.com/>
 - <http://diydrones.com/group/arduboard-user-group/forum>









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Active topics

	Topics
 	The Basic ROV Control System Wiring Manual (Rev. 1)
 	Making Threaded Prop Adapters
 	draw, thrust, and components

[[Go to page: 1 ... 6, 7, 8](#)]

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For underwater AUV, ROV, and Robotic enthusiasts

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- [Build Reports](#) [Using ROVs](#) [Guides](#) [Gallery](#) [Education](#)
- [Water/ Pressure Proofing](#) [Tethers](#) [ROV Electronics](#) [OpenROV 2.7](#)
- [OpenROV 2.6](#) [OpenROV 2.5](#) [OpenROV 2.3/2.4](#) [OpenROV 2.2](#)
- [Marketplace](#) [Add-on Components](#)

- [Germany Europe Sources](#) 39m
- [Some questions on ordering Openrov2.8 kit\(the unassembled one\)](#) 17h
- [Propeller Design](#) 1d
- [Tethers at high depth\(beyond 1000ft\)](#) 3d
- [Small air bubbles on main tube](#) 5d

Community R&D

Discussion and tracking of Community member led R&D projects

- [Cockpit-Plugins](#) [Projects](#) [Community R&D Open Talk](#)

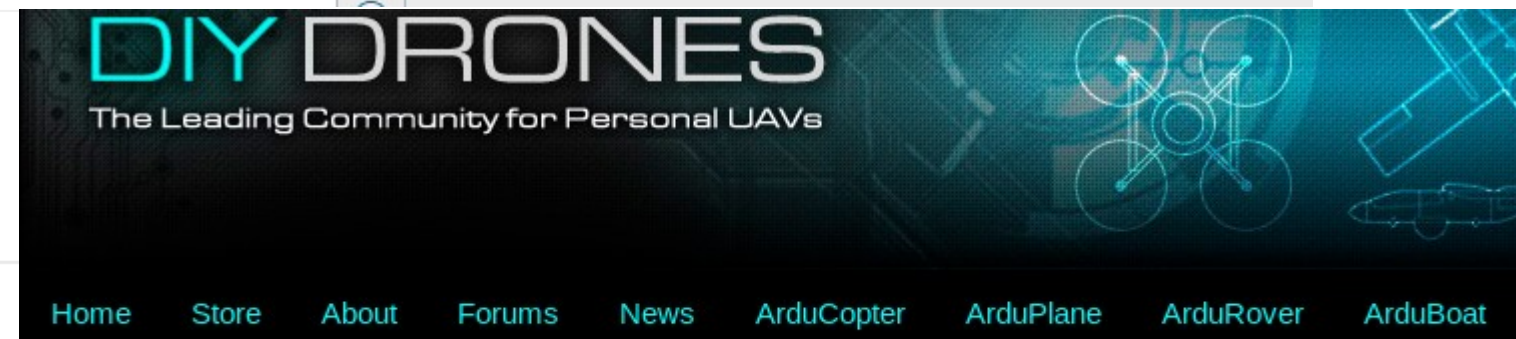
- [Waterproof 360 degree 4K Camera 12MP](#) 5d
- [Downward facing camera](#) 15d
- [Center of mass & center of buoyancy analysis](#) 29d
- [Openprop call out](#) Nov 13
- [360 degree camera](#) Nov 13

OpenROV R&D

Discussing R&D Projects that are led by OpenROV.

- [OpenROV Software](#) [User Interface](#) [OpenROV R&D Open Talk](#)
- [Projects](#) [Software-Bugs](#)

- [How to debug the cockpit code on my laptop?](#) 8h
- [\[SOLVED\] How long is the lead time to HongKong?](#) 23h
- [Feature: Change default keyboard control to be more like FPS gam](#)
- [30.0.3 software release notes](#) 12d
- [Testing Trident with attached Pavloads](#) 13d



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ArduBoat User Group Discussions (57)

Communities?

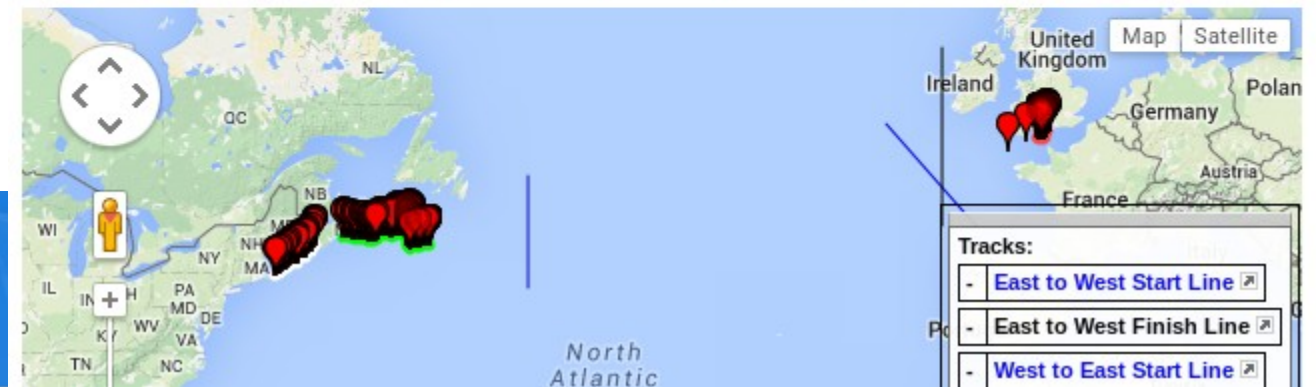
- Forums
- Competitions → papers by teams
 - World Robotic Sailing Competition (Portugal, <http://www.roboticsailing.org/>)
 - EURathlon (Italy, <http://www.eurathlon.eu/> previously sauc-e)
 - RoboBoat & RoboSub (USA, <http://www.auvsifoundation.org> , registration fee, 'College & High School teams') → papers from teams
 - Singapore AUV competition (<http://www.sauvc.org/>)
 - MATE ROV competition (USA, <http://www.marinetech.org>)



Communities?

- Forums
- Competitions → papers by teams
- Challenges
 - Microtransat
 - Shell Ocean XPrize

Boat	Team	Direction	Status	Latitude	Longitude	Last Update Time	Time Sailing	End Time/Status
Snoopy	Joker	West	Started: 2015-03-18 10:57:00	50.819	-0.1453	2015-03-30 21:32:34	12 days, 9 hours, 35 minutes	Ran aground 2015-03-30 21:32:35
ABoat Time	US Naval Academy	East	Started: 2015-06-13 22:02:00	43.797	-66.157	2015-06-23 07:28:21	9 days, 9 hours, 26 minutes	Picked up by fishing boat. 2015-06-23 07:29:00
Breizh Tigrisse	ENSTA- Bretagne and Dalhousie University	East	Started: 2015-09-01 18:30:00	43.784	-56.318	2015-10-04 01:01:09	32 days, 6 hours, 31 minutes	Disqualified, no position report for 10 days 2015-10-14 01:01:09



The \$7 Million Shell Ocean Discovery XPRIZE is a global competition challenging teams to advance deep-sea technologies for autonomous, fast and high-resolution ocean exploration.

The success of this prize will allow us to fully explore and map the ocean floor, and uncover our planet's greatest wonder and resource for the benefit of humanity. The National Oceanographic and Atmospheric Administration's (NOAA) \$1 million bonus prize will incentivize teams to develop technologies to detect the source of chemical and biological signals underwater.

Responsibility

- Legal \$STUFF
- Do not litter!
- Materials harmful to maritime environment?
- Invasion of maritime life forms
- Conductivity of (salty) water
→ skin resistance reduced



Can twitter help us find the owner of this ROV that washed ashore in Belize?
Please RT! #LostROV



RETWEETS 194 LIKES 39



6:24 PM - 12 Mar 2015



Reply to @JacobLevenson



Jake Levenson @JacobLevenson · Mar 15

@JacobLevenson sounds like the #LostROV belongs to Deep Tech Oil Services...sounds like they're in touch w folks to recover it.

<https://twitter.com/jacoblevenson/status/577071653982740480>

Call for Community

- IRC: #maritimerobotics on freenode
- Twitter: @lilafisch
- Email: lilafisch @ muc.ccc.de

1BB7 7178 15E8 94AC C08C 4FD8 315C 714C 0C7F 4570